

# UTILITY PATENT APPLICATION TRANSMITTAL

Only for new nonprovisional applications under 37 C.F.R. 1.53(b)

Attorney Docket No.

402/584

First Named Inventor or Application Identifier

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Title

A VIDEO CAMERA PIVOTING APPARATUS, A PIVOTING VIDEO  
CAMERA APPARATUS, AND A MONITORING SYSTEM WITH A  
PIVOTING VIDEO CAMERA

Express Mail Label No.

## APPLICATION ELEMENTS

See MPEP chapter 600 concerning utility patent application contents

ADDRESS TO:

Assistant Commissioner for Patents  
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1. ☒ Filing Fee as calculated below.2. ☒ Specification [Total Pages [ 25]]

(preferred arrangement set forth below)

- Descriptive title of the invention
- Cross References to Related Applications
- Statement Regarding Fed sponsored R & D
- Reference to Microfiche Appendix
- Background of the Invention
- Brief Summary of the invention
- Brief Description of the Drawings (if filed)
- Detailed Description
- Claim(s)
- Abstract of the Disclosure

3. ☒ Drawings (35 USC 113) [Total Pages [ 5]]

4. Oath or Declaration [Total Pages [ 2]]

- a. ☒ Newly executed (original or copy)
- b. ☐ Copy from a prior application (37 CFR 1.63(d))  
(for continuation/divisional with Box 17 completed)

☐ DELETION OF INVENTOR(S)

Signed statement attached deleting  
inventor(s) named in the prior application,  
see 37 CFR 1.63(d)(2) and 1.33(b)

5. ☐ Incorporation By Reference (useable if Box 4b is checked) The entire disclosure of the prior application, from which a copy of the oath or declaration is supplied under Box 4b, is considered as being part of the disclosure of the accompanying application and is hereby incorporated by reference therein.

6. ☐ Microfiche Computer Program (Appendix)
7. Nucleotide and/or Amino Acid Sequence Submission (if applicable, all necessary)

- a. ☐ Computer Readable Copy
- b. ☐ Paper Copy (identical to computer copy)
- c. ☐ Statement verifying identity of above copies

## ACCOMPANYING APPLICATION PARTS

8. ☒ Assignment Papers (cover sheet & document(s))
9. ☐ 37 CFR 3.73(b) Statement ☐ Power of Attorney
10. ☐ English Translation Document (if applicable)
11. ☒ Information Disclosure Statement (IDS)/PTO-1449 ☒ Copies of IDS Citations
12. ☐ Preliminary Amendment
13. ☒ Return Receipt Postcard (MPEP 503)  
(Should be specifically itemized)
14. ☐ Small Entity ☐ Statement filed in prior application,  
Statement(s) Status still proper and desired
15. ☒ Certified Copy of Priority Document(s)  
(if foreign priority is claimed)
16. ☐ Other:

17. If a CONTINUING APPLICATION, check appropriate box and supply the requisite information:

- ☐ Continuation ☐ Divisional ☐ Continuation-in-part (CIP) of prior application No. \_\_\_\_\_ / \_\_\_\_\_

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1-669-323397

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position.

## SUMMARY OF THE INVENTION

The aim of the present invention is to provide a superior video camera pivoting apparatus for pivoting a video camera, a superior pivoting video camera apparatus, 5 and a superior video monitoring system with a pivoting video camera.

According to the present invention, a video camera pivoting apparatus is provided which includes: a pivoting unit for pivoting a video camera at a pivoting speed, the video camera including a zoom mechanism and a zoom amount signal generation circuit for generating a zoom amount signal; a pivoting speed command signal generating circuit responsive to an operation for generating a pivoting speed command signal; and a speed controlling circuit for controlling the pivoting speed in accordance with the zoom amount signal and the pivoting speed command signal. In the video camera pivoting apparatus, the speed controlling circuit controls the pivoting speed in accordance with the zoom amount signal and the pivoting speed command signal such that the pivoting speed is relatively decreased from the pivoting speed command signal when the zoom amount signal indicates a telephoto side and is relatively increased from the pivoting speed command signal when the zoom signal indicates a wide-angle.

In the video camera pivoting apparatus, the pivoting speed command signal generation circuit includes a joystick mechanism and generates the pivoting speed command signal such that a value of the pivoting speed command signal increases at a first rate with respect to an operation angle of the joystick mechanism when the operation angle is not greater than a reference operation angle and at a second rate with respect to the operation angle of the joystick mechanism when the operation angle is greater than the reference operation angle, the second rate being greater than the first rate. In this case, the joystick mechanism includes a reaction force generation unit for generates a reaction force such that the reaction force increases at a third rate with respect to an operation angle of the joystick mechanism when the operation angle is not greater than the reference operation angle and at a fourth rate with respect to the operation angle of the joystick mechanism when the operation angle is greater than the reference operation angle, the fourth rate being greater than the third rate in order to inform the operator that the value of the pivoting speed command signal increases at the second rate. In this case, the reaction force generation unit includes first and second springs respectively having first and second spring constants. The reaction force is generated by the first

5 angle. In this case, the second spring constant may be greater than the first spring index.

include: a sequential control unit for storing a sequential program and generating another pivoting speed command signal in accordance with the sequential program; a detecting circuit for detecting that the pivoting speed command signal generation circuit generates the pivoting speed command signal in response to the operation; a switch circuit for supplying the pivoting speed command signal to the speed controlling circuit when the detecting circuit detects that the pivoting speed command signal generation circuit generates the pivoting speed command signal in response to the operation and supplying another pivoting speed command signal to the speed controlling circuit when the detecting circuit does not detect that the pivoting speed command signal generation circuit generates the pivoting speed command signal in response to the operation and supplying another pivoting speed command signal to the speed controlling circuit.

25           According to this invention, a pivoting video camera

apparatus is provided which includes: a video camera having  
a zoom lens mechanism; a zoom amount detection circuit  
responsive to the zoom lens mechanism for generating a zoom  
amount signal indicative of an amount of zooming of the  
5 zoom lens mechanism; a pivoting unit for pivoting the video  
camera at a pivoting speed; a pivoting speed command signal  
generating circuit for generating a pivoting speed command  
signal; and a speed controlling circuit for controlling the  
pivoting speed in accordance with the zoom amount signal  
10 and the pivoting speed command signal such that the  
pivoting speed is relatively decreased from the pivoting  
speed command signal when the zoom amount signal indicates  
a telephoto side and is relatively increased from the  
pivoting speed command signal when the zoom signal  
15 indicates a wide-angle.

According to this invention, a video monitoring  
system is provided which includes: a video camera unit  
including: a video camera having a zoom lens mechanism; a  
zoom amount detection circuit responsive to the zoom lens  
20 mechanism for generating a zoom amount signal indicative of  
an amount of zooming of the zoom lens mechanism; a pivoting  
unit for pivoting the video camera at a pivoting speed  
controlled in accordance with a speed control signal; and a  
monitor site including: a video monitor located remote from  
25 the video camera for displaying an image from the video

camera; a pivoting speed command signal generating circuit arranged adjacent to the video monitor for generating a pivoting speed command signal; and a speed control signal generation circuit for generating the speed control signal in accordance with the zoom amount signal and the pivoting speed command signal, wherein the speed control signal generation circuit generates the speed control signal such that the pivoting speed is relatively decreased from the pivoting speed command signal when the zoom amount signal indicates a telephoto side and is relatively increased from the pivoting speed command signal when the zoom signal indicates a wide-angle.

BRIEF DESCRIPTION OF THE DRAWINGS

The object and features of the present invention will become more readily apparent from the following detailed description taken in conjunction with the accompanying drawings in which:

Fig. 1 is a block diagram of a video monitoring system with a pivoting video camera of an embodiment of this invention;

Fig. 2 is a graphical drawing of this embodiment showing a relation between a pivoting angle speed and the operation angle of the joystick shown in Fig. 1;

Fig. 3 is a side view of the joystick of the first embodiment;

Fig. 4 is a graphical drawing of the embodiment showing a relation between the operation force and the joysticks shown in Fig. 1; and

Fig. 5 is a graphical drawing of the embodiment  
5 showing a table representing a relation between the  
pivoting angle speed and the operation angle  $\theta$  of the  
joysticks shown in Fig. 1; and

Fig. 6 is a block diagram of a modification of this invention.

10           The same or corresponding elements or parts are  
designated with like references throughout the drawings.

## DETAILED DESCRIPTION OF THE INVENTION

Hereinbelow will be described an embodiment of this invention.

15            Fig. 1 is a block diagram of a video monitoring  
system with a pivoting video camera of this embodiment.  
Fig. 2 is a graphical drawing of this embodiment showing a  
relation between a pivoting (panning or tilting) angle  
speed and the operation angle of the joystick shown in Fig.  
20 1. Fig. 3 is a side view of the joystick of the first  
embodiment.

The video monitoring system of this invention includes a video camera 1 for receiving an image and generating a video signal with a zoom mechanism 15, a  
25 pivoting unit 2 for supporting the video camera 1 and



panning and tilting the video camera 1 in accordance with a panning speed command signal 34a and a tilting speed command signal 36a, and a monitor site 3 for providing a monitor image in response to the video signal 11a to an operator, supplying a zoom command signal 32a to the zoom mechanism 15, and supplying a panning speed command signal 34a, and a tilting speed command signal 36a to the pivoting unit 2.

The video camera 1 includes an imaging circuit 11, the zoom mechanism 15 including a zoom lens unit 10, a driving circuit 12, and a zoom amount detection circuit 14. The imaging circuit 11 receives the image through the zoom lens unit 10 and generates the video signal 11a. The zoom lens unit 10 receives the image and forms the image on an imager (not shown) of the imaging circuit 11. The driving circuit 12 generates a zoom driving signal 12a in response to the zoom command signal 32a. A zoom motor 13 included in the zoom lens unit 10 drives the zoom lens assembly (not shown) of the zoom lens unit 10 to control a zoom amount. The zoom amount detection circuit 14 responsive to the zoom lens unit 10 generates the zoom amount signal 14a indicative of an amount of zooming of the zoom lens unit 10.

The video camera 1 and the pivoting unit 2 supporting the video camera 1 communicate with the monitor site by cables or a network such as a telephone line.

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The pivoting unit 2 includes a pivoting mechanism 21 including a pan motor 24 for providing panning the video camera 1 and a tilt motor 27 for providing tilting the video camera 1, a pan speed control circuit 22 for  
5 generating a panning speed signal 22a, a driving circuit 23 for driving the pan motor 24 in accordance with the panning speed signal 22a, a tilt speed control circuit 25 for generating a tilt speed signal 25a, a driving circuit 26 for driving the tilt motor 27 in accordance with the tilt  
10 speed signal 25a.

The monitor site 3 locates remote from the video camera 1 and the pivoting unit 2 and includes a video monitor 31 for displaying the monitor image in response to the video signal 11a from the video camera 1, a panning  
15 speed command signal generating circuit 37 arranged adjacent to the video monitor 31 for generating a panning speed command signal 34a, a tilt speed command signal generating circuit 38 arranged adjacent to the video monitor for generating a tilting speed command signal 36a.

20 The panning speed command signal generation circuit 37 includes a joystick 33 and an angle detection circuit 34 for detecting an operation angle of the joystick 33 and for generating the panning speed command signal 34a.

The tilt speed command signal generation circuit 38  
25 includes a joystick 35 and an angle detection circuit 36

for detecting an operation angle of the joystick 35 and for generating the tilt speed command signal 36a.

The video monitoring system is provided in a building at remote places or buildings remote from each other to monitor predetermined remote places. The video camera 1 and the pivoting unit 2 are arranged at a position suitable for monitoring. For example, the pivoting unit 2 is fixed to a wall of a building. The video camera 1 receives an image of a portion of the place and generates the video signal which is transmitted to the monitor site 3 through a cable or the like. The video camera 1 includes the zoom mechanism 15 to provide a wide-angle image, a standard angle image or a telephoto image. The pivoting unit 2 supports the video camera 1 and pans the video camera 1 (in the horizontal direction) in accordance with the panning speed command signal 34a and tilts the video camera 1 (in the vertical direction) in accordance with the tilting speed command signal 36a.

The monitor site 3 provides the monitor image received by the video camera 1 to the operator in response to the video signal 11a. The operator operates the zoom switch 32 to control the zoom mechanism 15 by supplying the zoom command signal 32a to the zoom mechanism 15 toward the telephoto side to more clearly watch the monitor image or toward the wide-angle to widely watch the monitor image.

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In the normal condition, the operator watches the monitor image in a wide-angle condition. When the operator is aware of a trouble on the monitor image, the operator operates the joysticks 33 and 35, and the zoom switch 32 to  
5 direct the video camera 1 to the trouble occurring place.

Then, the video camera 1 controls the amount of zoom in response to the zoom command signal 32a. On the other hand, the pivoting unit 2 pans and tilts the video camera 1 in response to the panning speed command signal 34a and  
10 tilting speed command signal 36a to direct the video camera to the trouble occurring place.

The joystick 33 is at an upright condition (rest position RP) when it is not operated and inclined with action by the operator. The angle detecting circuit 34  
15 detects the operation angle (inclined angel)  $\theta$  with a potentiometer 43 of which axis 42 is connected to an end of the joystick 33. The angle detection circuit 34 generates the panning speed command signal 34a in accordance with the operation angle of the joystick 33. The pan speed control  
20 circuit 22 generates the panning speed signal 22a in accordance with the zoom amount signal 14a and the panning speed command signal 34a such that the panning speed is relatively decreased from the panning speed command signal 34a when the zoom amount signal 14a indicates a telephoto  
25 side and is relatively increased from the panning speed

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command signal 34a when the zoom amount signal 34a indicates a wide-angle.

As shown in Fig. 2, the pan speed control circuit 22 generates the panning speed signal 22a in accordance with the zoom amount signal 14a and the panning speed command signal 34a. When the amount of zoom is at a standard angle 51, the pivoting (panning) angle speed signal is not compensated substantially, that is, the panning speed command signal 34a is outputted as the panning speed signal 22a as it is. On the other hand, when the amount of zoom is telephoto angle side 53, a  $\gamma > 1$  of the panning speed command signal 34a is relatively decreased to provide the panning speed signal 22a. Moreover, when the amount of zoom is wide angle side 52, the  $\gamma < 1$  of the panning speed command signal 34a is relatively increased to provide the panning speed signal 22a.

The driving circuit 23 drives the pan motor 24 in accordance with the panning speed signal 22a and the pan motor 24 rotates to pan the video camera 1.

The joystick 35 is at an upright condition when it is not operated and inclined with action by the operator. The angle detecting circuit 36 detects the operation angle (inclined angle) with a potentiometer 43 of which axis 42 is connected to an end of the joystick 35. The angle detection circuit 36 generates the tilting speed command

signal 34a in accordance with the operation angle of the joystick 35. The pan speed control circuit 25 generates the tilting speed signal 22a in accordance with the zoom amount signal 14a and the tilt speed command signal 36a such that the tilting speed is relatively decreased from the tilt speed command signal 36a when the zoom amount signal 14a indicates the telephoto side 53 and is relatively increased from the tilt speed command signal 36a when the zoom amount signal 34a indicates the wide-angle side 52.

As shown in Fig. 2, the tilt speed control circuit 25 generates the tilt speed signal 25a in accordance with the zoom amount signal 14a and the tilt speed command signal 36a. When the amount of zoom is at the standard angle 51, the tilt angle speed signal is not compensated, that is, the tilt speed command signal 36a is outputted as the tilt speed signal 25a as it is. On the other hand, when the amount of zoom is telephoto angle 53, a gamma of the tilting speed command signal 36a is relatively decreased (compensated) to provide the tilt speed signal 25a. Moreover, when the amount of zoom is wide angle side 52, the gamma of the tilt speed command signal 34a is relatively increased (compensated) to provide the tilt speed signal 25a.

The driving circuit 26 drives the tilt motor 27 in

accordance with the tilt speed signal 25a and the tilt motor 27 rotates to tilts the video camera 1.

As shown in Fig. 3, the joystick 33 includes a joystick lever 41, and a potentiometer 43 of which axis 42 is connected to the joystick lever 41, so that the operation angle  $\theta$  is detected by the potentiometer 43. The opposite end 46 of the joystick lever 21 is connected to an end of a spring 44 of which other end is connected to a case 27 of the joystick 33 to provide a reaction force to the operator when the operator inclines the lever 41 in the direction A and returns the joystick lever 21 to the rest position RP when an operation force is removed. The spring 45 receives the end 46 of the joystick lever 21 when the operation angle  $\theta$  exceeds a reference angle  $\theta_m$  to provide an additional second reaction force which is stronger than the reaction force only by the spring 44. This makes the reaction force stronger when the operation angle exceeds the reference angle  $\theta_m$ . That is, a spring constant  $\{k = W/\delta \text{ (Kg/mm)}\}$  of the spring 45 is higher than a spring constant of the spring 44.

The joystick lever 41 is also inclined to the opposite direction B and spring 44' and 45' also generates reaction forces similarly to pivot the video camera in the opposite direction.

Fig. 4 is a graphical drawing of the embodiment

showing a relation between the operation force and the joysticks 33 and 35. The joystick 33 or 35 inclines at a operation angle  $\theta$  in accordance with the operation force  $F$  applied by the operator. That is, in the joy stick 33 or 35, the springs 44, 45, 44', and 45' generates the reaction force such that the reaction force increases at a rate  $RT1$  ( $\gamma$ ) with respect to the operation angle of the joystick mechanism when the operation angle is not greater than the reference operation angle  $\theta_m$  and at a rate  $RT2$  with respect to the operation angle  $\theta$  of the joystick mechanism when the operation angle is greater than the reference operation angle  $\theta_m$ . The rate  $RT2$  is greater than the rate  $RT1$ .

The angle detection circuits 34 and 36 include ROM tables for generating the panning speed command signal 32a and the tilt speed command signal 36a in accordance with the detection of the operation angle of the joysticks 33 and 35, respectively.

Fig. 5 is a table of the embodiment showing a relation between the pivoting (panning and tilting) angle speed and the operation angle  $\theta$  of the joysticks 33 and 35.

The panning and tilt speed command signals 34a and 36a increase at a rate  $RT3$  when the operation angles  $\theta$  of the joysticks 33 and 35 are not greater than the reference angle  $\theta_m$ , respectively. Then, the panning and tilt speed command signals 34a and 36a increase at a rate  $RT4$  when the

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operation angles  $\theta$  of the joysticks 33 and 35 are greater than the reference angle  $\theta_m$ , respectively. The rate RT4 is greater than the rate RT3. Therefore, the panning motor 24 and the tilt motor 27 are driven at an extremely high speed  
5 when the operation angles of the joysticks 33 and 35 are greater than the reference angle  $\theta_m$ . Accordingly, the pan motor 24 and the tilt motor 27 reach to max speeds rapidly, so that the interval for directing the monitor screen to the target is shortened.

10 As shown in Fig. 4 the reaction force to the lever 41 is more increased when the operation angle  $\theta$  exceeds the reference angle  $\theta_m$  at an inflection point INF1 and as shown in Fig. 5, the pivoting (panning and tilting) speeds are more increased when the operation angle exceeds the  
15 reference angle  $\theta_m$  at an inflection point INF2. The inflection point INF1 in Fig. 4 corresponds to the inflection point INF2 in Fig. 5. Therefore, more increase in the reaction force above the inflection point INF1 provides an attention of more increase in the pivoting  
20 speed to the operator.

In the embodiment of this invention, the video camera 1 and the pivoting unit 2 are separated from each other. However, it is also possible that the video camera 1 and the pivoting unit 2 are united.

25 Fig. 6 is a block diagram of a modification of this

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The sequential control circuit 40 stores a sequential program for sequentially generating another zoom command signal, another panning speed command signal, and another tilt speed command signal to provide the monitor image to the operator at the monitor site in an automatically monitoring mode.

When the operator operates either of the joystick 33 or 35, a potential from the angle detection circuit 34 or 36 deviates from the potential corresponding to the rest position RP, for example, deviates from zero volt.

The comparator and logic circuit 71 detects that either of the potential from the angle detection circuit 34 or 36 deviates from zero volt more than a predetermined voltage. If the comparator and logic circuit 71 detects that either of the potential from the angle detection circuit 34 or 36 deviates from zero volt more than a predetermined voltage, the switches 72 to 74 supplies the zoom command signal 32a, the panning speed command signal 34a, and the tilt speed command signal 36a instead another zoom command signal 40a, another panning speed command

signal 40b, and another tilt speed command signal 40c.

That is, the operation of the joystick 33 or 35 overrides the sequential control circuit 40.

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4. The video camera pivoting apparatus as claimed in claim 3, wherein said joy stick mechanism includes reaction force generation means for generates a reaction force such that said reaction force increases at a third rate with respect to an operation angle of said joystick mechanism when said operation angle is not greater than a reference operation angle and at a fourth rate with respect to said operation angle of said joystick mechanism when said operation angle is greater than said reference operation angle, said fourth rate being greater than said third rate in order to inform the operator that said value of said pivoting speed command signal increases at said second rate.

5. The video camera pivoting apparatus as claimed in claim 4, wherein said reaction force generation means comprises first and second springs respectively having first and second spring constants, said reaction force is generated by said first spring when said operation angle is not greater than said reference operation angle, and said reaction force is generated by said first and second springs when said operation angle is greater than said reference operation angle.

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6. The video camera pivoting apparatus as claimed in claim 5, wherein said second spring constant is greater than said first spring index.

15 7. A pivoting video camera apparatus comprising:

a video camera having a zoom lens mechanism;

zoom amount detection means responsive to said zoom lens mechanism for generating a zoom amount signal indicative of an amount of zooming of said zoom lens

20 mechanism;

pivoting means for pivoting said video camera at a pivoting speed;

pivoting speed command signal generating means for generating a pivoting speed command signal; and

25 speed controlling means for controlling said

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a video camera having a zoom lens mechanism;

zoom lens mechanism for generating a zoom amount signal

15

pivoting means for pivoting said video camera unit

a monitor site including:

20

arranged adjacent to said video monitor for generating a

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speed control signal generation means for

generating said speed control signal in accordance with said zoom amount signal and said pivoting speed command signal, wherein said speed control signal generation means generates said speed control signal such that said pivoting speed is relatively decreased from said pivoting speed command signal when said zoom amount signal indicates a telephoto side and is relatively increased from said pivoting speed command signal when said zoom signal indicates a wide-angle.

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sequential control means for storing a sequential  
program and generating another pivoting speed command  
15 signal in accordance with said sequential program;

detecting means for detecting that said pivoting  
speed command signal generation means generates said  
pivoting speed command signal in response to said operation;  
and

20           switch means for supplying said pivoting speed  
command signal to said speed controlling means when said  
detecting means detects that said pivoting speed command  
signal generation means generates said pivoting speed  
command signal in response to said operation and supplying  
25 said another pivoting speed command signal to said speed

25



controlling means when said detecting means does not detect  
that said pivoting speed command signal generation means  
generates said pivoting speed command signal in response to  
said operation and supplying said another pivoting speed  
5 command signal to said speed controlling means.

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ABSTRACT OF THE DISCLOSURE

A pivoting unit pivots a video camera at a pivoting speed. The video camera includes a zoom mechanism and a zoom amount signal generation circuit for generating a zoom amount signal. A pivoting speed command signal generating circuit responsive to an operation generates a pivoting speed command signal and a speed controlling circuit controls the pivoting speed in accordance with the zoom amount signal and the pivoting speed command signal.

10 Controlling is made such that the pivoting speed is relatively decreased from the pivoting speed command signal when the zoom amount signal indicates a telephoto side and is relatively increased from the pivoting speed command signal when the zoom signal indicates a wide-angle. A

15 joystick generating the pivoting speed command signal includes two coil springs for generating a reaction force which is made stronger when the operation angle of thereof exceeds a reference. The pivoting speed is also accelerated when the operation angle exceeds the reference.

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Fig. 1

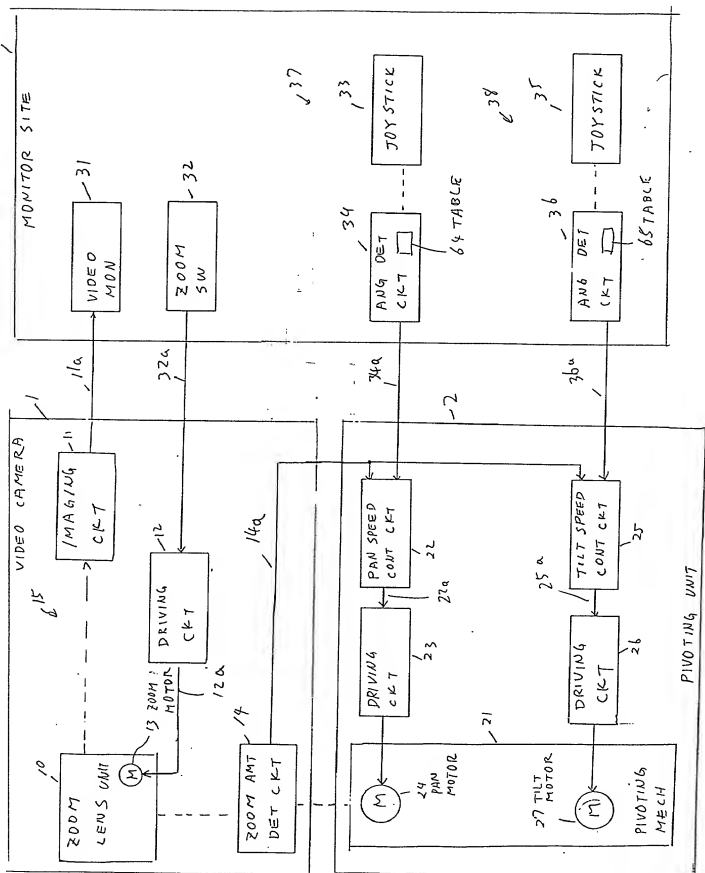


FIG. 2

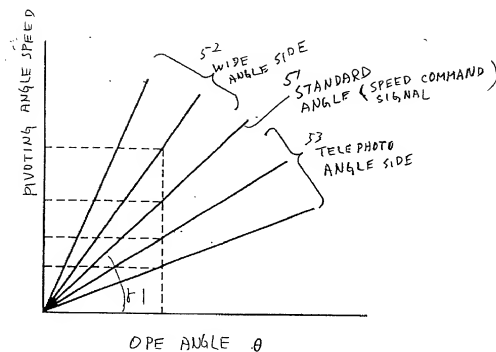
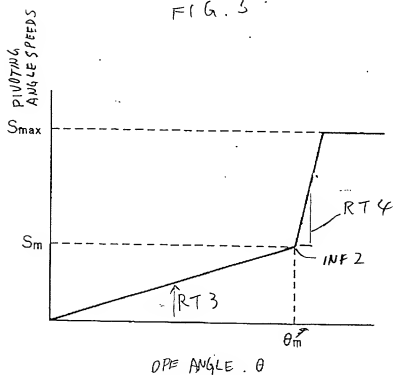


FIG. 5



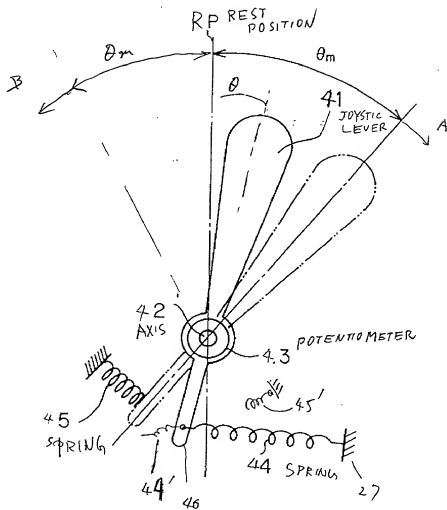
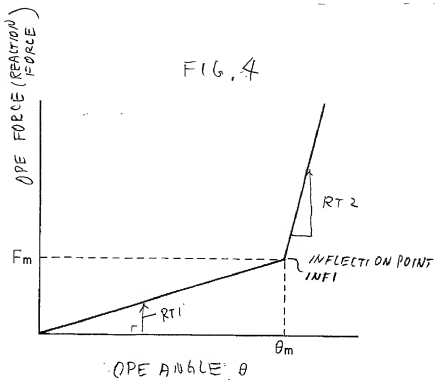


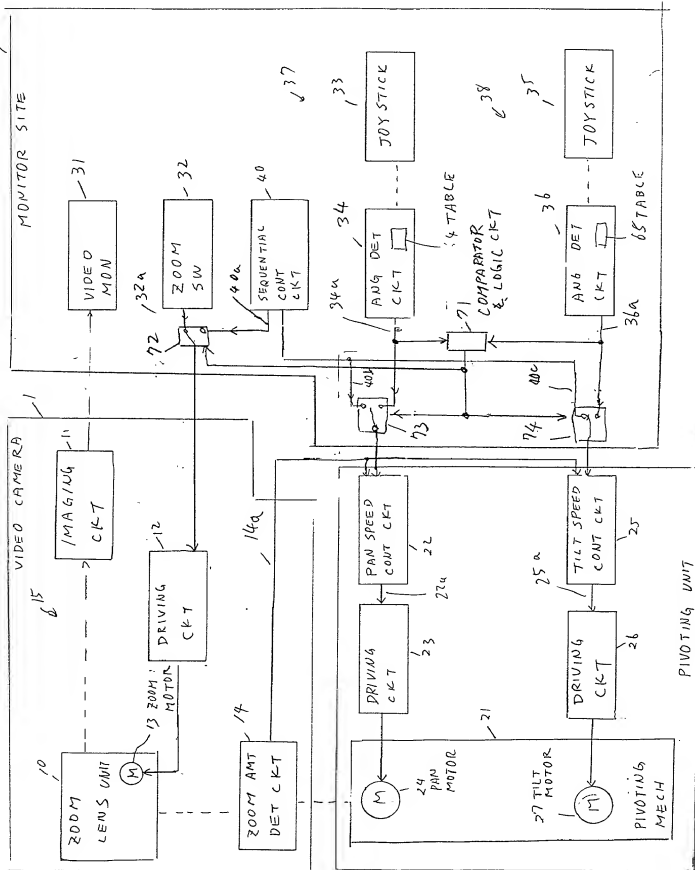
FIG. 4



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Fig. 6

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# DECLARATION FOR PATENT APPLICATION

Page One of Two

As a below-named inventor, I hereby declare that:

My residence, post office address and citizenship are as stated below next to my name.

I believe I am the original, first and sole inventor (if only one name is listed below) or an original, first and joint inventor (if plural names are listed below) of the subject matter which is claimed and for which a patent is sought on the invention entitled: A VIDEO CAMERA PIVOTING APPARATUS, A PIVOTING VIDEO CAMERA APPARATUS, AND A MONITORING SYSTEM WITH A PIVOTING VIDEO CAMERA the specification of which: (check one)

☒ [X] is attached hereto. ☐ [ ] was filed on 19, as United States Patent Application Serial No. or PCT International Application Number, and was amended on 19 (if applicable).

I hereby state that I have reviewed and understand the contents of the above-identified specification, including the claims, as amended by any amendment referred to above.

I acknowledge the duty to disclose information which is material to the patentability of this application in accordance with 37 CFR § 1.56(a).

Prior Foreign Application(s): I hereby claim foreign priority benefits under 35 U.S.C. § 119(a)-(d) or § 365(b) of any foreign application(s) for patent or inventor's certificate listed below, or § 365(a) of any PCT international application which designated at least one country other than the United States of America, listed below and have also identified below any foreign application for patent or inventor's certificate having a filing date before that of the application on which priority is claimed:

Application No.	Country	Filing Date	Priority Claimed
10-167514	Japan	June 15, 1998	[X] [ ]
(Application No.)	(Country)	(Day/Month/Year Filed)	Yes No
			[ ] [ ]
(Application No.)	(Country)	(Day/Month/Year Filed)	Yes No
			[ ] [ ]
(Application No.)	(Country)	(Day/Month/Year Filed)	Yes No

I hereby claim the benefit under Title 35, United States Code § 119(e) of any United States provisional application(s) listed below:

Application No.	Filing Date

I hereby claim the benefit under 35 U.S.C. § 120 of any United States application(s) listed below and, insofar as the subject matter of each of the claims of this application is not disclosed in the prior United States application in the manner provided by 35 U.S.C. § 112, first paragraph, I acknowledge the duty to disclose material information as defined in 37 CFR § 1.56(a) which occurred between the filing date of the prior application and the national or PCT international filing date of this application:

(U.S. Application Serial No.)	(U.S. Filing Date)	(Status—patented, pending, abandoned)
(U.S. Application Serial No.)	(U.S. Filing Date)	(Status—patented, pending, abandoned)

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I hereby declare that all statements made herein of my own knowledge are true and that all statements made on information and belief are believed to be true; and further that these statements are made with the knowledge that willful false statements and the like so made are punishable by fine or imprisonment, or both, under 18 U.S.C. § 1001 and that such willful false statements may jeopardize the validity of the application or any patent issued thereon.

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## DECLARATION FOR PATENT APPLICATION

Page Two

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